



# A homoclinic hierarchy

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**Abstract**

Homoclinic bifurcations in autonomous ordinary differential equations provide useful organizing centres for the analysis

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A homoclinic orbit of an autonomous ordinary differential equation is a solution  $x_H(t)$  of the equation  $\dot{x} = f(x, \mu)$  such that  $x_H(t) \rightarrow x_0$  as  $t \rightarrow \pm\infty$  and  $x_H(0) \neq x_0$ . In typical (e.g. non-Hamiltonian) systems, a homoclinic orbit is not a structurally stable feature. However, in certain circumstances, a homoclinic orbit can be structurally stable. This is the case for a homoclinic orbit of a piecewise-smooth system. In this paper, we study the bifurcations of a homoclinic orbit of a piecewise-smooth system. We show that, for a certain class of piecewise-smooth systems, a homoclinic orbit can be structurally stable. In particular, we show that, for a certain class of piecewise-smooth systems, a homoclinic orbit can be structurally stable. In particular, we show that, for a certain class of piecewise-smooth systems, a homoclinic orbit can be structurally stable.

orbit which exists at  $\mu = \mu_H$ . If this is the case we can show that, for a certain class of piecewise-smooth systems, a homoclinic orbit can be structurally stable. In particular, we show that, for a certain class of piecewise-smooth systems, a homoclinic orbit can be structurally stable.

recent work has been stimulated by a series of papers [1-4]. In particular, it has been shown that, for a certain class of piecewise-smooth systems, a homoclinic orbit can be structurally stable. In particular, we show that, for a certain class of piecewise-smooth systems, a homoclinic orbit can be structurally stable.

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cations, for which the homoclinic orbit loops several times through the tubular neighbourhood of the original homoclinic orbit.

on the linearized flow near the stationary point. Suppose that the stationary point is hyperbolic. Then, after a change of coordinates we may assume that it is at the origin for all values of  $\mu$  which are of interest and the family of differential equations can be written in the form

$$\dot{x} = Ax + F(x, \mu) \tag{1}$$

for  $x \in \mathbb{R}^n$ ,  $n \geq 2$ . Here  $F(0, \mu) = 0$ ,  $A$  is a constant  $n \times n$  matrix and  $F$  is smooth and contains only nonlinear terms. Assume that if  $\mu = 0$  then the system has a homoclinic orbit  $x_H(t)$  bicurvatric

no homoclinic orbits close to  $x_H$  (by close we mean that for  $n$  sufficiently small  $|x(t) - x_H(t)| < \epsilon$  for all  $t \in (-\infty, \infty)$ ).

It can be divided into two sets,  $\{\lambda_i\}$ ,  $i = 1, \dots, n_u$ , and  $\{\nu_i\}$ ,  $i = 1, \dots, n_s$ ,  $n_s + n_u = n$ , such that  $\text{Re}(\lambda_i) > 0$  and  $\text{Re}(\nu_i) < 0$ . These can be ordered so that

$$\text{Re}(\nu_1) \leq \dots \leq \text{Re}(\nu_{n_s}) \leq \text{Re}(\lambda_1) < \dots < \text{Re}(\lambda_{n_u}).$$

Typically, trajectories which tend to  $x = 0$  as  $t \rightarrow \infty$  do so tangential to the eigenspace corresponding to those eigenvalues with  $\text{Re}(\nu_i) = \text{Re}(\nu_1)$ , which we refer to as the dominant stable eigenvalues. Simi-

larily, trajectories which tend to  $x = 0$  as  $t \rightarrow -\infty$  do so tangential to the eigenspace corresponding to the dominant unstable eigenvalues, i.e. those with  $\text{Re}(\lambda_i) = \text{Re}(\lambda_1)$ . We assume that the homoclinic orbit  $x_H(t)$  is typical in this sense.

There are four generic cases (up to time reversal)

of a homoclinic orbit. In the first case the dominant eigenvalues is  $\{\nu_1, \lambda_1\}$ , with  $\nu_1, \lambda_1 \in \mathbb{R}$ , and  $\nu_1 + \lambda_1 \neq 0$ .

In this case (which can occur for  $n \geq 2$ ), provide some genericity conditions are satisfied, the homoclinic bifurcation creates a single periodic orbit which exists in either  $\mu < 0$  or  $\mu > 0$  [2]. As  $\mu$  tends to zero from the appropriate side the periodic orbit

is stable if  $\nu_1 + \lambda_1 < 0$ , otherwise it is a saddle.

(II) *Saddle-focus homoclinic orbit.* The set of

dominant eigenvalues is  $\{\nu_2, \nu_1, \lambda_1\}$ , with  $\nu_1 = \nu_2^* \in \mathbb{C} \setminus \mathbb{R}$ ,  $\lambda_1 \in \mathbb{R}$ , and  $\text{Re}(\nu_1) + \lambda_1 \neq 0$ .

This case can occur if  $n \geq 3$ . There are two subcases.

(IIa)  $\text{Re}(\nu_1) + \lambda_1 < 0$ . The bifurcation is essentially the same as case (I).

(IIb)  $\text{Re}(\nu_1) + \lambda_1 > 0$ . If  $\mu = 0$  there are chaotic solutions in a tubular neighbourhood of the homoclinic orbit. There are sequences of saddle-node bifurcations accumulating on  $\mu = 0$  from both sides, and sequences of (geometrically more complicated) homoclinic bifurcations accumulating on  $\mu = 0$ .

(III) *Bifocal homoclinic orbit.* The set of dominant eigenvalues is  $\{\nu_1, \nu_2, \lambda_1, \lambda_2\}$  with  $\nu_1 = \nu_2^* \in \mathbb{C} \setminus \mathbb{R}$  and  $\lambda_1 = \lambda_2^* \in \mathbb{C} \setminus \mathbb{R}$ .

Similar to that described for case (IIb), but typically there are more complicated homoclinic bifurcations accumulating on  $\mu = 0$ .

The results sketched above form the basis of

the study of the saddle-node, period-doubling and Hopf bifurcations in local bifurcation theory. Whilst there are many examples of cases (I) and (II) in the literature it is extraordinary that (to the best of our knowledge) no unambiguous examples of case (III) have been described to date. There are examples with homoclinic orbits to stationary points satisfying

the conditions of case (III), which have a very special bifurcation structure [11,12]. A piecewise linear example of case III is described in Ref. [13], and here we use the same ideas, described below, to construct a smooth (only

in one dimension) example of case III. In so doing we derive a hierarchy of equations in two, then three, and then four dimensions. Each equation is obtained from the previous system by extending it in an appropriate manner to one more dimension. In principle this construction could be extended to obtain a hierarchy of equations in higher dimensions.

Simple examples of interesting dynamical phenomena have been constructed using a variety of

techniques. Arnéodo, Coulet and Tresser [14] used

In coordinates  $(x_u, x_s, z)$  defined by  $x = x_s e_s +$

the adjoint eigenvectors of the linear part of a "seed" equation to define the coupling between the equation and an extra variable in such a way that the linear part of the new equation has the desired spectral condition. We then appeal to perturbation theory and numerical experiment to suggest that the dynamically interesting behaviour (in this case, the existence of a homoclinic orbit) is inherited by the new equation from the "seed" equation. The new equation can in turn be treated as a "seed" equation and the process can be repeated. The use of adjoint eigenvectors is not entirely necessary (one could try trial and error) but ensures that complete control of the spectral properties of the stationary point is maintained throughout the hierarchy.

$$\dot{x}_u = \lambda_1 x_u, \quad \dot{x}_s = \nu_1 x_s - z, \quad \dot{z} = \epsilon_1 x_s + \nu_1 z, \quad (6)$$

with eigenvalues  $\lambda_1 > 0$  and  $\nu_1 \pm \sqrt{-\epsilon_1}$ . Hence if  $\epsilon_1 > 0$  the linear part of (3) satisfies the conditions of case (IIa). Since homoclinic bifurcations are typically of codimension one we expect (at least for small  $\epsilon_1 > 0$ ) there to be a curve of homoclinic bifurcations in  $(\mu, \epsilon_1)$  parameter space of the form  $\mu = H(\epsilon_1)$  with  $H(0) = 0$ . If this curve does exist then (5) provides an example of case (IIa).

Similarly, if we consider

$$\dot{w} = \epsilon_2 (e_u^\dagger \cdot x) + \lambda_1 w, \quad \dot{x} = Ax - we_u + f(x, \mu), \quad (7)$$

are easy to find, so let

$$\dot{x} = Ax + f(x, \mu) \quad (3)$$

and  $\lambda_1 \pm \sqrt{-\epsilon_2}$  and so, using (4), under similar assumptions we obtain homoclinic bifurcations of class (III) in reverse time if  $\epsilon_2 > 0$ .

tion of the plane to itself which contains only nonlinear terms,  $f(0, \mu) = 0$  and there is a homoclinic orbit, asymptotic to the stationary point at the origin in both forward and backward time. If  $\lambda_1 > 0$  and  $\nu_1 < 0$  and  $\epsilon_1 < \lambda_1$  and

$$\dot{w} = \epsilon_2 (e_u^\dagger \cdot x) + \lambda_1 w, \quad \dot{x} = \epsilon_1 (e_s^\dagger \cdot x) + \nu_1 x, \quad (8)$$

we should be able to find bifocal homoclinic bifurcations (case (III)) if  $\epsilon_1$  and  $\epsilon_2$  are small and positive.

$$|\nu_1| > \lambda_1 \quad (4)$$

eigenvectors (see e.g. Ref. [16] for a discussion of adjoint eigenvectors in dynamical systems). Thus  $A^T e_s^\dagger = \nu_1 e_s^\dagger$ ,  $A^T e_u^\dagger = \lambda_1 e_u^\dagger$ ,  $e_s^\dagger \cdot e_u = e_u^\dagger \cdot e_s = 0$  and the eigenvectors can be normalized so that  $e_s^\dagger \cdot e_s = e_u^\dagger \cdot e_u = 1$ .

Eq. (3) is the first member of the homoclinic hierarchy. Now define the extended system

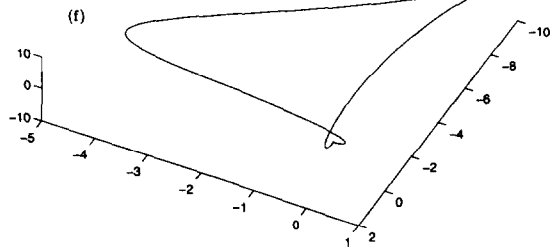
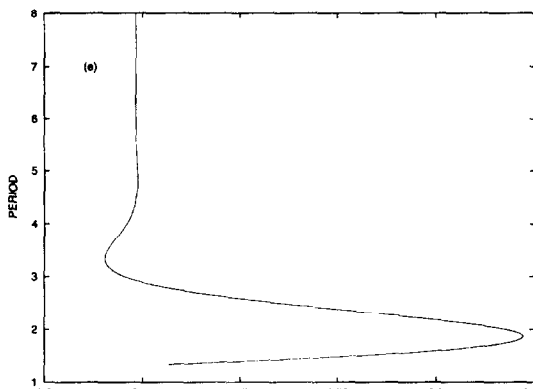
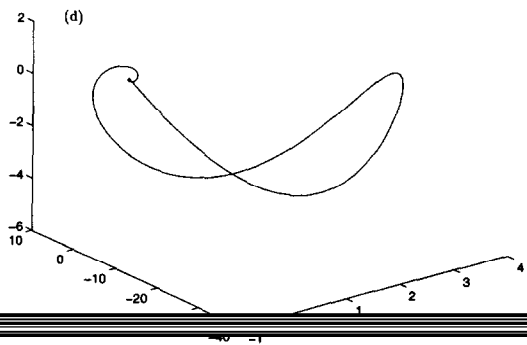
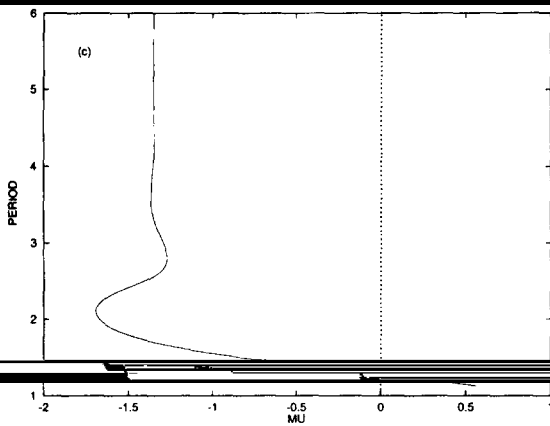
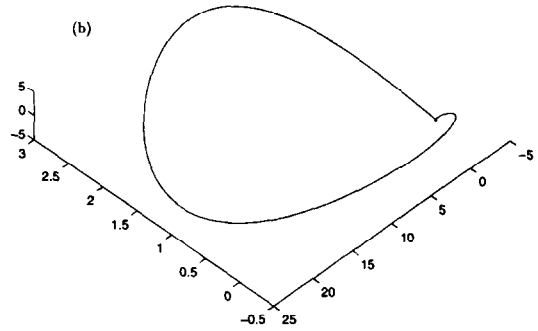
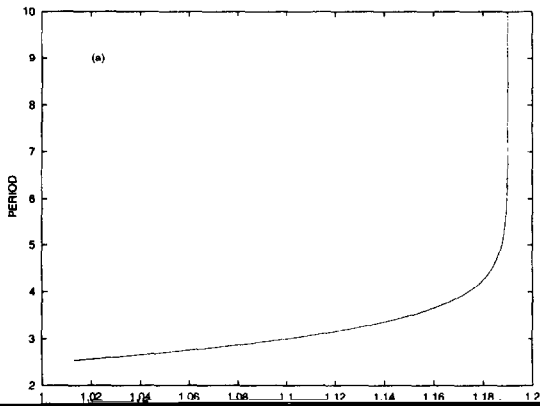
$$\dot{x} = Ax - ze_s + f(x, \mu), \quad \dot{z} = \epsilon_1 (e_s^\dagger \cdot x) + \nu_1 z. \quad (5)$$

dimensional system

$$\dot{x} = y, \quad \dot{y} = 6x - y - 6x^2 + \mu xy, \quad (9)$$

for which there is strong numerical evidence that a homoclinic orbit exists if  $\mu = \mu_H \approx 1.164371$ . For this example, in the notation of (3),

$$A = \begin{pmatrix} 0 & 1 \\ 6 & -1 \end{pmatrix}, \quad f(x, \mu) = \begin{pmatrix} 0 \\ -6x^2 + \mu xy \end{pmatrix}, \quad (10)$$



(a) Bifurcation diagram for Eq. (3) with  $\epsilon = 0.1$  showing the approach of the simple periodic orbit to the homoclinic orbit. (b) A homoclinic orbit of (3) with  $\mu = 1.6$  and  $\omega = 2.557395$ . (c) As (a) using Eq. (2) with  $\mu = 1.6$ . (d) A homoclinic orbit of (2) with  $\mu = 1.6$  and  $\omega = 1.251245$ . (e) Bifurcation diagram for Eq. (3) with  $\epsilon = 0.1$  showing the approach of the simple periodic orbit to the homoclinic orbit. (f) A homoclinic orbit of (3) with  $\mu = 1.6$  and  $\omega = 2.557395$ .

so  $\lambda = 2$ ,  $\nu = -3$  and (4) is satisfied. A simple

the periodic orbit to a bifocal homoclinic orbit

$$\begin{aligned} \dot{u} &= 5(2) - u(1) \\ \dot{v} &= 5(-3) - v(-1) \end{aligned} \quad (12)$$

homoclinic orbit.

We consider that a trajectory that follows a periodic orbit to very high period provides very strong evidence for the existence of the homoclinic orbit, but we have also done further numerical experiments to add more weight to our claim. The local stable manifold of the origin is tangential to the plane spanned by  $e_1 = (0, 0, 0, 1)^T$  and  $e_2$  (extended

$$\begin{aligned} \dot{w} &= \epsilon_2(3x + y) + 2w, \quad \dot{x} = y - \frac{1}{5}z - \frac{1}{5}w, \\ \dot{y} &= 6x - y + \frac{1}{5}z - \frac{1}{5}w - 6x^2 + \mu xy, \end{aligned} \quad (13)$$

Although our argument for the existence of homoclinic orbits in (12) (and hence (5) and (7)) is

manifold is tangential to the plane spanned by  $e_u$  (extended to  $\mathbb{R}^4$ ) and  $e_4 = (1, 0, 0, 0)^T$ . If a homoclinic orbit exists, then the stable manifold

exists over a broad range of values of  $|\epsilon_i|$  ( $i = 1, 2$ ). We use larger values of the param-

computed approximation shown in Fig. 11 suggests that a point of intersection lies in the hyperplane

features of the orbits, in particular the spiralling motion near the stationary point, is much clearer at these values. In all cases, the approximate parameter value of the homoclinic bifurcation is obtained by following a periodic orbit to very high period with changing parameter. The homoclinic orbit can be thought of as the limit of this orbit as the period tends to infinity.

of this intersection we integrated points on a circle of initial conditions enclosing the origin on the linear approximation to the local unstable manifold forwards in time and monitored the first intersection of

Fig. 1 shows the results of three sets of numerical experiments obtained using AUTO [17]. In Figs. 1a, 1b we have set  $\epsilon_2 = w = 0$  (equivalent to choosing (5) with  $A$  and  $f$  given by (10) and the adjoint system by (11)). This figure shows a plot of the

$2 < x < 2.5$  (if such an intersection exists). In this way we obtained a series of points on a curved line segment, U. A similar exercise in reverse time using initial conditions on the linear approximation to the local stable manifold provided a second curved line segment, S. This numerical experiment was repeated at different values of  $\mu$ . Using polynomial interpolation to obtain approximations for U and S between

illustrating the familiar logarithmic increase in period as the orbit approaches the homoclinic orbit in case (IIa) with  $\epsilon_1 = 0.1$ . In Fig. 1b we show a homoclinic orbit for this system with  $\epsilon_1 = 16$  and

was calculated using Newton's method on the parametrized curves. Now let  $n$  be the vector obtained in this way with  $\mu = 0.64$ , and  $u(\mu)$  the vector obtained at nearby values of  $\mu$ . These results

Figs. 1c, 1d shows similar plots for  $\epsilon_1 = z = 0$  and  $\epsilon_2 = 16$  (equivalent to (7);  $z = 0$  is an invariant manifold). In this case, as expected for (IIb), the periodic orbit undergoes a sequence of saddle-node bifurcations as its period tends to infinity. The homoclinic orbit at  $\mu \approx -1.351357$  is illustrated in Fig. 1d.

$\text{sign}(n \cdot u(\mu)) |u(\mu)|$ .

A zero of this signed distance function thus indicates an intersection between S and U, and hence the existence of a homoclinic orbit. If, in addition, the sign of the signed distance function changes, then the family of differential equations parametrized by  $\mu$  passes transversely through the codimension one surface of systems with homoclinic orbits. We found, using a circle of radius  $10^{-4}$  for the initial condi-

Finally, Figs. 1e, 1f show the analogous pictures

tions and numerically obtained normalized eigenvectors, that for  $0.55 < \mu < 0.64$  the signed distance function is positive (and equal to 0.004617 at  $\mu = 0.64$  whilst for  $0.65 < \mu < 0.71$  the signed distance function is negative (and equal to  $-0.002365$  at  $\mu = 0.65$ ). This strongly suggests that for some values of  $\mu$  between 0.64 and 0.65 there is a zero of the distance function, and hence a homoclinic orbit for the differential equation (12). Linear interpolation between  $\mu = 0.64$  and  $\mu = 0.65$  gives an approximate value of  $\mu = 0.645$  for the homoclinic bifurcation, in excellent agreement with the value obtained by following periodic orbits.

We have written down a hierarchy of differential equations which illustrate the four fundamental homoclinic bifurcations. In particular, we have obtained a smooth example of a bifocal homoclinic bifurcation (case III). So far as we are aware, this is the first such example (in Ref. [13] a piecewise linear example is studied, for which the existence of a bifocal homoclinic bifurcation can be proved using perturbation theory, but this does not satisfy the standard smoothness conditions of Shilnikov's results [13] although the results can be trivially ex-

are non-generic, having either a Hamiltonian or re-

The observant reader will have noted that one unfolding of the degenerate Jordan normal form

$$\begin{pmatrix} \lambda_1 & 1 & 0 & 0 \\ 0 & \lambda_1 & 0 & 0 \\ 0 & 0 & \nu_1 & 1 \\ 0 & 0 & 0 & \nu_1 \end{pmatrix} \quad (13)$$

We look at the existence of bifocal homoclinic orbits in this light elsewhere [8]: in particular, we explore several codimension two bifurcations involving bifocal homoclinic bifurcations. The normal form (13) has codimension greater than two, and we consider this to be too large for useful analysis in the absence of some concrete physical motivation.

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